



# High Voltage 3-Phase Motor Driver

#### **Features and Benefits**

- Each half-bridge circuit consists of a pre-driver circuit that is completely independent from the others
- Protection against simultaneous high- and low-side turning on
- Bootstrap diodes with series resistors for suppressing inrush current are incorporated
- CMOS compatible input (3.3 to 5 V)
- Designed to minimize simultaneous current through both high- and low-side IGBTs by optimizing gate drive resistors
- UVLO protection with auto restart
- Overcurrent protection with off-time period adjustable by an external capacitor

 Fault (FO indicator) signal output at protection activation: UVLO (low side only), OCP, and STP

Proprietary power DIP package

Package: Power DIP

Not to scale

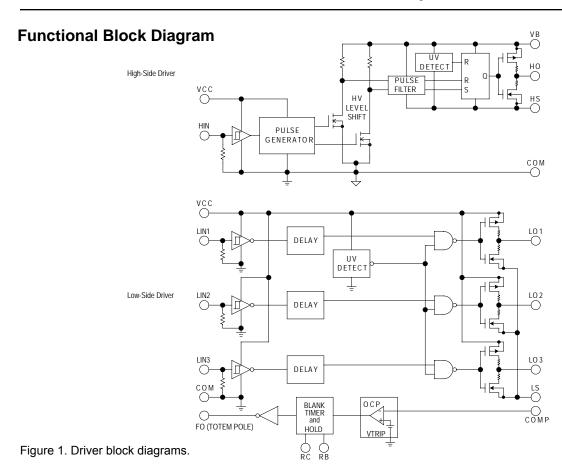
### **Description**

The SSM1001MA inverter power module (IPM) device provides a robust, highly-integrated solution for optimally controlling 3-phase motor power inverter systems and variable speed control systems used in energy-conserving designs to drive motors of residential and commercial appliances. These ICs take 85 to 253 VAC input voltage, and 15 A (continuous) output current. They can withstand voltages of up to 600 V (IGBT breakdown voltage).

The SSM1000M series employs a new proprietary DIP package. The IC itself consists of all of the necessary power elements (six IGBTs), pre-driver ICs (four), and flyback diodes (six), needed to configure the main circuit of an inverter, as well as a shunt resistor. This enables the main circuit of the inverter to be configured with fewer external components than traditional designs.

Applications include residential white goods (home applications) and commercial appliance motor control:

- Air conditioner compressor
- Washing machine main drum



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#### **Selection Guide**

		IGBT Breakdown Voltage, V <sub>CES</sub> (min) (V)	IGBT Saturation Voltage, V <sub>CE(sat)</sub> (typ) (V)	Output Current		
Part Number	Packing			Continuous, I <sub>O</sub> (max) (A)	Pulsed, I <sub>OP</sub> (max) (A)	
SSM1001MA	8 pieces per tube	600	1.6	15	30	

## **Absolute Maximum Ratings**, valid at $T_A = 25$ °C

Characteristic Symb		Remarks	Rating	Unit
Main Supply Voltage V <sub>BB</sub>		Between VBB and GND	450	V
Logic Supply Voltage V <sub>CC</sub>		Between VCC and COM	20	V
Bootstrap Voltage	V <sub>BS</sub>	Between VB and HS (U,V, and W phases)	20	V
Output Current, Continuous	Io	T <sub>C</sub> = 25°C	15	Α
Output Current, Pulsed	I <sub>OP</sub>	PW ≤ 5 ms	30	Α
Input Voltage	V <sub>IN</sub>		-0.5 to 7	V
RC Pin Input Voltage	V <sub>RC</sub>	Between RC and COM	20	V
Allowable Power Dissipation	P <sub>D</sub>	T <sub>C</sub> = 25°C, 1 element operating (IGBT)	33	W
Allowable Power Dissipation for Shunt Resistance	P <sub>DR</sub>	T <sub>C</sub> = 25°C	6	W
The most Decistance (I metion to Cook)		1 element operating (IGBT)	3.79	°C/W
Thermal Resistance (Junction to Case)	R <sub>θJC</sub>	1 element operating (FWD)	5.43	°C/W
Case Operating Temperature	T <sub>COP</sub>		-20 to 100	°C
Junction Temperature (IGBT)	TJ		150	°C
Storage Temperature	T <sub>stg</sub>		-40 to 150	°C
Isolation Voltage V <sub>iso</sub>		Between exposed thermal dissipation pad and each pin; for 1 minute, AC	1500	V <sub>RMS</sub>

## **Recommended Operating Conditions**

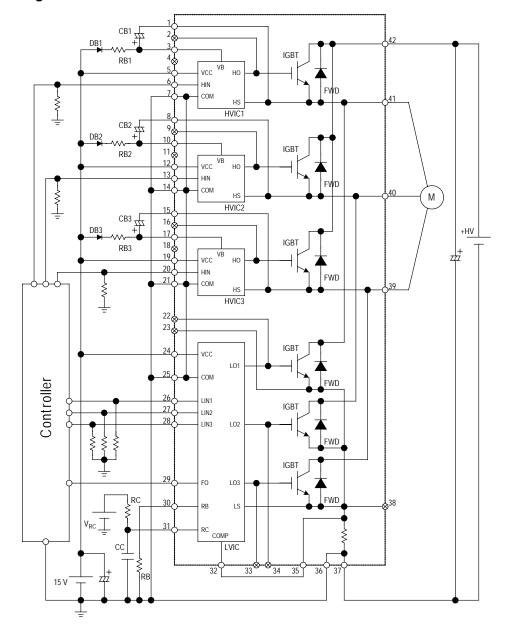
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Characteristic	Symbol	Remarks	Min.	Тур.	Max.	Units
Main Supply Voltage	V <sub>BB</sub>	Between VBB and LS	_	300	450	V
Logic Supply Voltage	V <sub>CC</sub>	Between VCC and COM	13.5	_	16.5	V
Dead Time	t <sub>dead</sub>		2.5	_	_	μs
Junction Temperature	TJ		_	_	125	°C

All performance characteristics given are typical values for circuit or system baseline design only and are at the nominal operating voltage and an ambient temperature,  $T_A$ , of 25°C, unless otherwise stated.





## **Typical Application Diagram**







# High Voltage 3-Phase Motor Driver

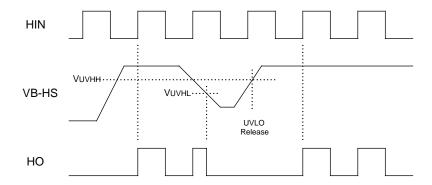
#### ELECTRICAL CHARACTERISTICS, valid at $T_A$ =25°C, unless otherwise noted

Characteristics	Symbol	Conditions	Min	Тур	Max	Units
Logic Supply Voltage	V <sub>CC</sub>	Between VCC and COM	13.5	_	16.5	V
Logic Supply Current	Icc	V <sub>CC</sub> = 15 V	_	_	8	mA
In such Malda and	V <sub>IH</sub>	V <sub>CC</sub> = 15 V, output on	4	_	_	V
Input Voltage	V <sub>IL</sub>	V <sub>CC</sub> = 15 V, output off	-	_	1	V
Input Voltage Hysteresis	V <sub>Ihys</sub>	V <sub>CC</sub> = 15 V	_	8.0	_	V
	I <sub>IHH</sub>	High side, V <sub>CC</sub> = 15 V, V <sub>IN</sub> = 5 V	_	50	100	μA
Input Current	I <sub>ILH</sub>	High side, V <sub>CC</sub> = 15 V, V <sub>IN</sub> = 0 V	_	_	2	μA
Input Guirent	I <sub>IHL</sub>	Low side, $V_{CC}$ = 15 V, $V_{IN}$ = 5 V	_	50	100	μA
	I <sub>ILL</sub>	Low side, $V_{CC}$ = 15 V, $V_{IN}$ = 0 V	_	_	2	μA
	$V_{UVHL}$	High side, V <sub>CC</sub> = 15 V	9.5	_	11.5	V
Undervoltage Lock Out	$V_{UVHH}$	nigit side, v <sub>CC</sub> = 15 v	10.0	_	12.0	V
Officervoltage Lock Out	$V_{UVLL}$	Low side, V <sub>CC</sub> = 15 V	10.0	_	12.0	V
	$V_{UVLH}$	Low side, VCC - 13 V	10.5	_	12.5	V
FO Terminal Output Voltage	$V_{FOL}$	V <sub>CC</sub> = 15 V	0	_	1.0	V
1 O Terminal Output Voltage	$V_{FOH}$	V66 - 13 V	4.0	_	5.5	V
FO Terminal Output Current	I <sub>FOL</sub>	V <sub>CC</sub> = 15 V, V <sub>FOL</sub> = 1 V	_	_	-1.6	mA
	I <sub>FOH</sub>	V <sub>CC</sub> = 15 V, V <sub>FOH</sub> = 4 V	_	_	1	mA
Overcurrent Protection Trip Voltage	V <sub>TRIP</sub>	V <sub>CC</sub> = 15 V	0.45	0.50	0.55	V
Overcurrent Protection Hold Time	t <sub>p1</sub>	$V_{RC}$ = 15 V, $R_{C}$ = 1 M $\Omega$ , $C_{C}$ = 1000 pF, $R_{B}$ = 30 k $\Omega$	_	260	_	μs
Overcurrent i Totection Flora Time	t <sub>p2</sub>	$V_{RC}$ = 5 V, $R_{C}$ = 1.5 M $\Omega$ , $C_{C}$ = 2200 pF, $R_{B}$ = 30 k $\Omega$	_	5	_	ms
Blanking Time	t <sub>blank</sub>	$V_{CC}$ = 15 V, $R_B$ = 30 k $\Omega$	_	1.6	_	μs
IGBT Breakdown Voltage	V <sub>CES</sub>	$V_{CC} = 15 \text{ V}, I_C = 250 \mu\text{A}, V_{IN} = 0 \text{ V}$	600	_	-	V
IGBT Leakage Current	I <sub>CES</sub>	$V_{CC} = 15 \text{ V}, V_{CE} = 600 \text{ V}, V_{IN} = 0 \text{ V}$	_	_	1	mA
IGBT Saturation Voltage	V <sub>CE(sat)</sub>	$V_{CC} = 15 \text{ V}, I_C = 15 \text{ A}, V_{IN} = 5 \text{ V}$	_	1.6	2.0	V
Diode Forward Voltage	V <sub>F</sub>	$V_{CC} = 15 \text{ V}, I_F = 15 \text{ A}, V_{IN} = 0 \text{ V}$	_	2.0	2.4	V
Diode Recovery Time	t <sub>rr</sub>	$I_F = 15 \text{ A}, \text{ di / dt} = 100 \text{ A/}\mu\text{s}$	_	50	_	ns
	t <sub>dH(on)</sub>	$V_{BB} = 280 \text{ V}, V_{CC} = 15 \text{ V}, I_{C} = 15 \text{ A}, 0 \text{ V} \leq V_{IN} \leq 5 \text{ V},$ inductive load	_	0.5	_	μs
Switching Time, High Side	t <sub>rH</sub>		_	0.1	_	μs
Switching Time, Fight Side	t <sub>dH(off)</sub>		_	0.7	_	μs
	t <sub>fH</sub>		_	0.5	_	μs
	t <sub>dL(on)</sub>		_	0.4	_	μs
Switching Time Low Side	t <sub>rL</sub>		_	0.1	-	μs
Switching Time, Low Side	t <sub>dL(off)</sub>	- -		0.5	_	μs
	t <sub>fL</sub>			0.5	_	μs
Shunt Resistance	Rs	I <sub>R</sub> = 15 A	24.2	25	25.8	mΩ



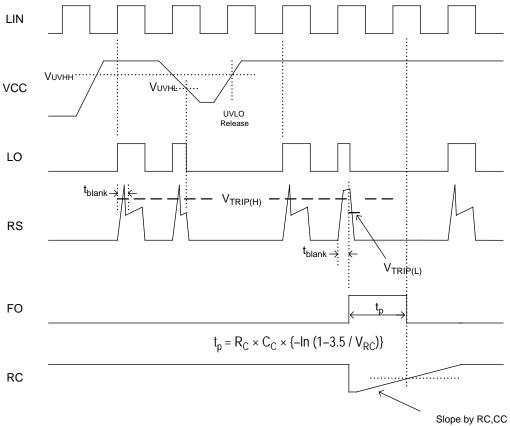


High Side Driver Input/Output Timing Diagrams



After UVLO is released, IC operation is started by the first rising edge of input

### Low Side Driver Input/Output Timing Diagrams



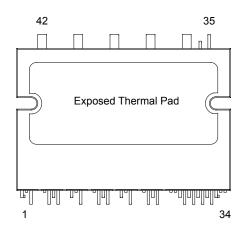
After UVLO is released, IC operation is started by the first rising edge of input

After RC charging and releasing, the OCP operation is started by the first rising edge of input



# High Voltage 3-Phase Motor Driver

## **Pin-out Diagram**



#### **Terminal List Table**

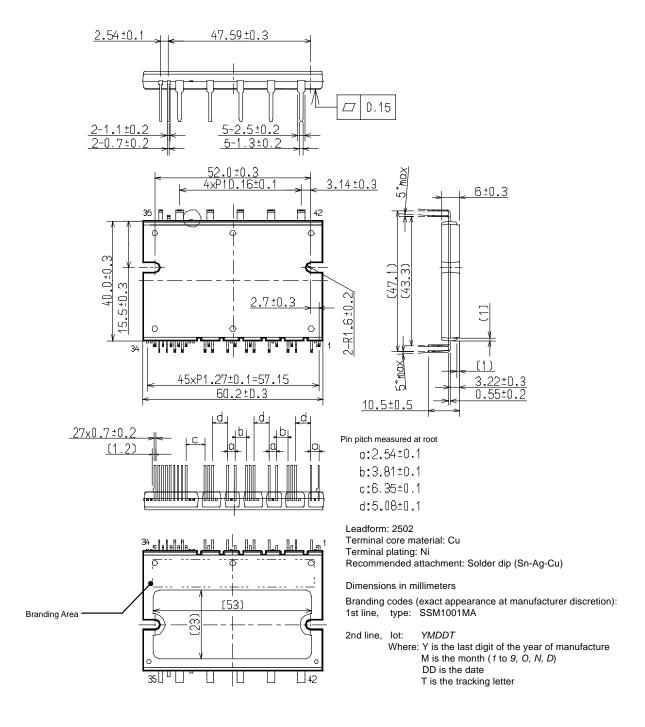
1 HS1 High-side floating supply ground (U phase) 2 NC Low-side IGBT gate (U phase) 2 NC High-side IGBT gate (U phase) 3 VB1 High-side floating supply voltage (U phase) 4 NC NC 5 VCC1 Control circuit supply voltage (U phase) 6 HIN1 Signal input for high-side (U phase) 7 COM1 Logic supply ground (U phase) 8 HS2 High-side floating supply ground (V phase) 9 NC High-side IGBT gate (V phase) 10 VB2 High-side floating supply voltage (V phase) 11 NC NC 12 Control circuit supply voltage (V phase) 13 HIN2 Signal input for high-side (V phase) 14 COM2 Logic supply ground (V phase) 15 HS3 High-side floating supply ground (W phase) 16 NC High-side floating supply voltage (W phase) 17 GND Main supply voltage (W phase) 18 RSPOS Shunt resistor terminal, negating the side of the si	
3 VB1 High-side floating supply voltage (U phase)  4 NC NC  5 VCC1 Control circuit supply voltage (U phase)  6 HIN1 Signal input for high-side (U phase), active high  7 COM1 Logic supply ground (U phase)  8 HS2 High-side floating supply ground (V phase)  9 NC High-side IGBT gate (V phase)  10 VB2 High-side floating supply voltage (V phase)  11 NC NC  12 VCC2 Control circuit supply voltage (V phase)  13 HIN2 Signal input for low-side (V phase)  14 COM2 Logic supply ground (V phase)  36 RSPOS Shunt resistor terminal, positi	,
4 NC NC  NC Signal input for low-side (U phase)  HIN1 Signal input for high-side (U phase), active high  COM1 Logic supply ground (U phase), active high  HIN2 Signal input for low-side (U phase)  High-side floating supply ground (V phase)  NC High-side IGBT gate (V phase)  NC High-side floating supply voltage (V phase)  HIN2 NC  NC Signal input for low-side (W phase)  COMP Feedback comparator terminal  NC NC Signal input for high-side (V phase)  HIN2 Signal input for high-side (V phase), active high  HIN2 Signal input for high-side (V phase)  Low-side IGBT gate (V phase)  HIN3 High-side floating supply ground (W phase)  RSPOS Shunt resistor terminal, positi	
5 VCC1 Control circuit supply voltage (U phase) 6 HIN1 Signal input for high-side (U phase), active high 7 COM1 Logic supply ground (U phase) 8 HS2 High-side floating supply ground (V phase) 9 NC High-side IGBT gate (V phase) 10 VB2 High-side floating supply voltage (V phase) 11 NC NC 12 COMP Feedback comparator terminal 12 VCC2 Control circuit supply voltage (V phase) 13 HIN2 Signal input for low-side (U phase) 14 COM2 Logic supply ground (V phase) 15 HS3 High-side floating supply yound (W phase) 16 LIN1 Signal input for low-side (U phase) 27 LIN2 Signal input for low-side (W phase) 28 LIN3 Signal input for low-side (W phase) 29 FO Fault output for overcurrent or setting resistor 29 RB Blanking time setting resistor 30 RB Blanking time setting resistor 31 RC Overcurrent protection setting 32 COMP Feedback comparator terminal 33 NC Low-side IGBT gate (W phase) 34 NC Low-side IGBT gate (W phase) 35 RSPOS Shunt resistor terminal, positi	
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7 COM1 Logic supply ground (U phase)  8 HS2 High-side floating supply ground (V phase)  9 NC High-side IGBT gate (V phase)  10 VB2 High-side floating supply voltage (V phase)  11 NC NC  12 COMP Feedback comparator terminal  12 VCC2 Control circuit supply voltage (V phase)  33 NC Low-side IGBT gate (W phase)  14 COM2 Logic supply ground (V phase)  35 RSPOS Shunt resistor terminal, positi	ase), active high
8 HS2 High-side floating supply ground (V phase) 9 NC High-side IGBT gate (V phase) 30 RB Blanking time setting resistor 10 VB2 High-side floating supply voltage (V phase) 31 RC Overcurrent protection setting 11 NC NC 32 COMP Feedback comparator termina 12 VCC2 Control circuit supply voltage (V phase) 33 NC Low-side IGBT gate (W phase) 13 HIN2 Signal input for high-side (V phase), active high 14 COM2 Logic supply ground (V phase) 15 HS3 High-side floating supply ground (W phase) 36 RSNEG Shunt resistor terminal, negative forminal in the side of the sid	ase), active high
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10 VB2 High-side floating supply voltage (V phase)  11 NC NC  12 VCC2 Control circuit supply voltage (V phase)  13 HIN2 Signal input for high-side (V phase), active high  14 COM2 Logic supply ground (V phase)  15 HS3 High-side floating supply ground (W phase)  31 RC Overcurrent protection setting  32 COMP Feedback comparator terminal  33 NC Low-side IGBT gate (W phase)  34 NC Low-side IGBT gate (V phase)  35 RSPOS Shunt resistor terminal, positing  36 RSNEG Shunt resistor terminal, negative	ndition detected
11 NC NC 32 COMP Feedback comparator terminal 12 VCC2 Control circuit supply voltage (V phase) 33 NC Low-side IGBT gate (W phase) 13 HIN2 Signal input for high-side (V phase), active high 34 NC Low-side IGBT gate (V phase) 14 COM2 Logic supply ground (V phase) 35 RSPOS Shunt resistor terminal, positing 15 HS3 High-side floating supply ground (W phase) 36 RSNEG Shunt resistor terminal, negative 15 Note 1	erminal
12 VCC2 Control circuit supply voltage (V phase) 13 HIN2 Signal input for high-side (V phase), active high 14 COM2 Logic supply ground (V phase) 15 HS3 High-side floating supply ground (W phase) 16 RSNEG Shunt resistor terminal, positi	resistor terminal
13 HIN2 Signal input for high-side (V phase), active high 14 COM2 Logic supply ground (V phase) 15 HS3 High-side floating supply ground (W phase) 36 RSNEG Shunt resistor terminal, negative floating supply ground (W phase)	I
14 COM2 Logic supply ground (V phase)  15 HS3 High-side floating supply ground (W phase)  36 RSNEG Shunt resistor terminal, negative supply ground (W phase)	)
15 HS3 High-side floating supply ground (W phase) 36 RSNEG Shunt resistor terminal, negative	l
3 11 3 17 3 17 7 7 7 7 7 7 7 7 7 7 7 7 7	e phase
16 NC High-side IGBT gate (W phase) 37 GND Main supply voltage GND	ve phase
17 VB3 High-side floating supply voltage (W phase) 38 NC Low-side IGBT emitter	
18 NC NC 39 W Output for W phase	
19 VCC3 Control circuit supply voltage (W phase) 40 V Output for V phase	
20 HIN3 Signal input for high-side (W phase), active high 41 U Output for U phase	
21 COM3 Logic supply ground (W phase) 42 VBB Main DC bus supply voltage	





# High Voltage 3-Phase Motor Driver

#### PACKAGE OUTLINE DRAWING





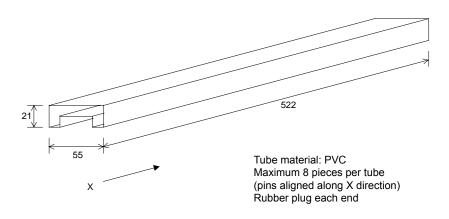
Leadframe plating Pb-free. Device composition complies with the RoHS directive.

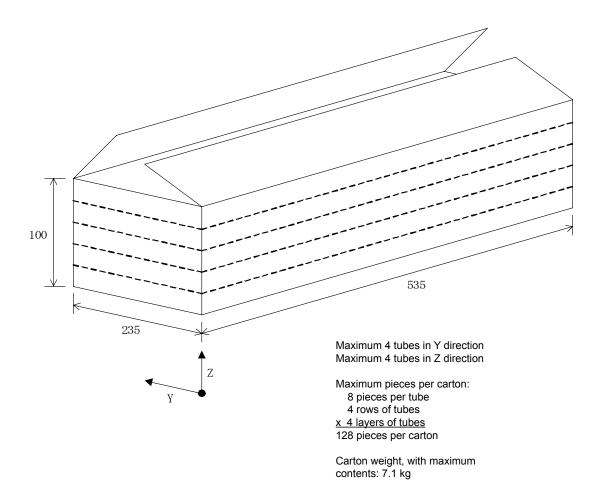




### **PACKING SPECIFICATION**

Dimensions in millimeters









# High Voltage 3-Phase Motor Driver

**WARNING** — These devices are designed to be operated at lethal voltages and energy levels. Circuit designs that embody these components must conform with applicable safety requirements. Precautions must be taken to prevent accidental contact with power-line potentials. Do not connect grounded test equipment.

The use of an isolation transformer is recommended during circuit development and breadboarding.

Because reliability can be affected adversely by improper storage environments and handling methods, please observe the following

#### **Cautions for Storage**

- Ensure that storage conditions comply with the standard temperature (5°C to 35°C) and the standard relative humidity (around 40 to 75%); avoid storage locations that experience extreme changes in temperature or humidity.
- Avoid locations where dust or harmful gases are present and avoid direct sunlight.
- Reinspect for rust on leads and solderability of products that have been stored for a long time.

#### **Cautions for Testing and Handling**

When tests are carried out during inspection testing and other standard test periods, protect the products from power surges from the testing device, shorts between adjacent products, and shorts to the heatsink.

#### Remarks About Using Silicone Grease with a Heatsink

- When silicone grease is used in mounting this product on a heatsink, it shall be applied evenly and thinly. If more silicone grease than required is applied, it may produce stress.
- Volatile-type silicone greases may permeate the product and produce cracks after long periods of time, resulting in reduced heat radiation effect, and possibly shortening the lifetime of the
- Our recommended silicone greases for heat radiation purposes, which will not cause any adverse effect on the product life, are indicated below:

Type		Suppliers
	G746	Shin-Etsu Chemical Co., Ltd.
	YG6260	GE Toshiba Silicone Co., Ltd.
	SC102	Dow Corning Toray Silicone Co., Ltd.

#### **Heatsink Mounting Method**

Torque When Tightening Mounting Screws. The recommended tightening torque for this product package type is: 78.4 to 88.2 Nocm (8.0 to 9.0 kgf•cm).

#### Soldering

When soldering the products, please be sure to minimize the working time, within the following limits:

260±5°C 10 s 380±5°C

Soldering iron should be at a distance of at least 1.5 mm from the body of the products

#### **Electrostatic Discharge**

- When handling the products, operator must be grounded. Grounded wrist straps worn should have at least 1  $\mbox{M}\Omega$  of resistance to ground to prevent shock hazard.
- Workbenches where the products are handled should be grounded and be provided with conductive table and floor mats.
- When using measuring equipment such as a curve tracer, the equipment should be grounded.
- When soldering the products, the head of soldering irons or the solder bath must be grounded in other to prevent leak voltages generated by them from being applied to the products.
- The products should always be stored and transported in our shipping containers or conductive containers, or be wrapped in aluminum foil.





# High Voltage 3-Phase Motor Driver

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# High Voltage 3 Phase Motor Driver



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